# On the stability of large ecological communities <br> [when an ecosystem breaks] 

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## Regime shifts



Conditions


Conditions


Conditions

## Regime shifts



## Regime shifts



Conditions

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Conditions


## Regime shifts



Conditions

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Conditions

[Scheffer et al., Nature 2001]

## Resilience and stability



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( $-\lambda^{*}$ determines the speed to return to equilibrium)

## Resilience and stability


$\lambda^{*}$ (largest eigenvalue of A )

$$
\begin{gathered}
\lambda^{*}<0 \text { stable } \\
\lambda^{*}>0 \text { unstable }
\end{gathered}
$$

$\lambda^{*}=0$ critical
$(-\lambda$ * determines the speed to return to equilibrium)

## Random matrix approach

$$
\begin{aligned}
\frac{d x_{i}}{d t} & =f_{i}(\underline{x}) \\
A_{i j} & =\left.\frac{\partial f_{i}}{\partial x_{j}}\right|_{\underline{x}^{*}}
\end{aligned}
$$

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model A

- A is large
- A is random (some stochastic rule to fill its entries)


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model A

- A is large
- A is random (some stochastic rule to fill its entries) the question:
what is the largest eigenvalue of A?
$\mathrm{p}\left(\mathrm{A}_{\mathrm{ij}}, \mathrm{A}_{\mathrm{j}}\right)$


## Why large and random?

## $p\left(\mathrm{~A}_{\mathrm{ij}}, \mathrm{A}_{\mathrm{ji}}\right)$

## Why large and random?

$30 \%$ pairs are interacting


## $\mathrm{p}\left(\mathrm{A}_{\mathrm{ij}}, \mathrm{A}_{\mathrm{ji}}\right)$

## Why large and random?

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$\mathrm{p}\left(\mathrm{A}_{\mathrm{ij}}, \mathrm{A}_{\mathrm{j}}\right)$
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100\% pairs are interacting

$\mathrm{p}\left(\mathrm{A}_{\mathrm{ij}}, \mathrm{A}_{\mathrm{j}}\right)$

## Why large and random?




100\% pairs are interacting


## Anatomy of a random matrix



## Anatomy of a random matrix



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## If the interactions are random

- only 4 important parameters (instead of size ${ }^{2}$ )
- a realization behaves as the average


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- only 4 important parameters (instead of size ${ }^{2}$ )
- a realization behaves as the average
...but interactions are not structureless
four examples:
- directionality
- modules / communities
- effect of the fixed point
- space


## - only 4 important parameters (instead of size ${ }^{2}$ ) - a realization behaves as the average

four examples:

- directionality
- modules / communities
- effect of the fixed point
- space
[Allesina, Grilli, Barbaas, Tang, Maritan, Nature Communications, 2015 .


GRANDIBVS EXIGVI SVVNT P P I S C C E S PISCIBVS ESCA.

## Cascade model

Big Fish Eat Little Fish


Pieter Bruegel the Elder, 1557

Cascade model


Cohen et al., 1990
order S species
species $i$ has probability $C$ of eating any of the preceding species produces acyclic graphs

## The eyeball



## Our strategy: eyeball = eye + ball



## Eigenvalues of A lay on a circumference

negative mean

positive mean

direction determined by the mean

## Eigenvalues of B are uniform in an ellipse





# It is possible to derive a new stability criterion for structured food-webs 



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## The stability criterion works well for empirical foodwebs

[empirical network
structure]
coefficient determined
using allometric scaling

## The stability criterion works well for empirical foodwebs



# - only 4 important parameters (instead of size²) - a realization behaves as the average 

four examples:

- directionality
- modules / communities
- effect of the fixed point
- space
[Grilli, Rogers and Allesina, Nature Communications, 2016]


## Communities




## Full characterization of the effect of modularity

|  |
| :---: |
|  |  |
|  |  |


[Grilli, Rogers and Allesina, Nature Communications, 2016]

## Usually destabilizing (but effect depends on interactions)



## "effect depends on interactions" is more general



# - only 4 important parameters (instead of size²) - a realization behaves as the average 

[Gibbs, Grilli, Rogers and Allesina, arXiv:1708.08837]

## Stability in an explicit model

$$
\frac{d x_{i}(t)}{d t}=\phi_{i}\left(x_{i}(t)\right) H_{i}\left(\sum_{j} A_{i j} x_{j}(t)\right)
$$

## Stability in an explicit model

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\left.\frac{\partial f_{i}}{\partial x_{j}}\right|_{x^{*}}=M_{i j}=\underbrace{\text { random matrix }}_{\text {random vector }}
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## Stability in an explicit model

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\left.\frac{\partial f_{i}}{\partial x_{j}}\right|_{x^{*}}=M_{i j}=X_{i} A_{i j}
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## Stability in an explicit model



SDA $0.25 \triangle 0.5 \square 0.75$

## For large random matrices stability is determined uniquely by interactions


$d \bigcirc 0.025 \triangle 0.05 \square 0.1$

## Measuring moments of interactions



Traditionally: infer $\mathrm{N}^{2}$ interaction from N time series

# - only 4 important parameters (instead of size²) - a realization behaves as the average 

- space
[Grilli, Barabais and Allesina, Plos Comp Bio 2015]


## Metapopulation


local death + dispersion

Persistence if eigenvalue of dispersion matrix is larger than death rate

## Eigenvalue depends on everything



## The eigenvalue depends on one effective parameter



## Measuring moments of interactions



Traditionally: infer $\mathrm{N}^{2}$ interaction from N time series
Can we directly infer the moments
(or more generally the statistical properties) of the interactions?

## Take home messages

Universality: lot of details do not matter
Few features of networks are important for stability

Network structure alone is not sufficient

## Acknowledgments

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